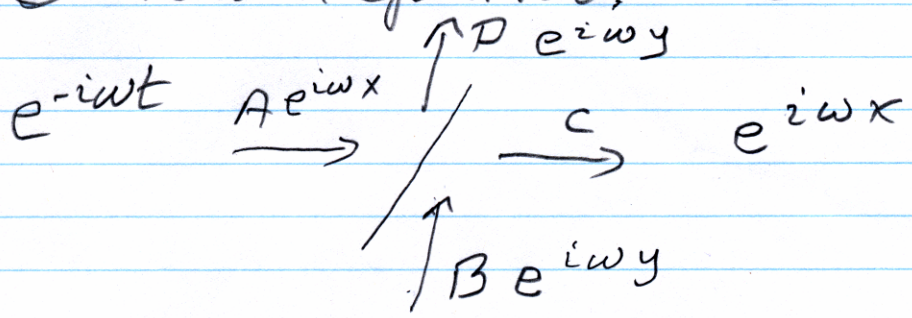


Parts of Interferometer:

① Beam splitter, -50-50.



Assume
$$\begin{pmatrix} C \\ D \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} A \\ B \end{pmatrix}$$

② EM as scalar field.

$$\partial_t \vec{D} = +\nabla \times \vec{H} \quad \eta^2 E = \eta^2 D$$

$$\partial_t \vec{B} = -\nabla \times \vec{E} \quad H = B$$

Prop in x-y plane. $E_z = \text{polom.}$

$$\begin{aligned} \eta^2 \partial_t^2 E_z &= -\nabla \times \frac{\partial B}{\partial t} = -\nabla \times (\nabla \times D) \\ &= -\partial_z \underbrace{(\nabla \cdot E)}_{=0} + \nabla^2 E_z \end{aligned}$$

$$\xi = \frac{x+y}{\sqrt{2}} \quad \eta = \frac{x-y}{\sqrt{2}}$$

Beam split. surface at $\eta = 0$.

2

{ what is actual Beam splitter transfer function? - I can not find this. It is important.

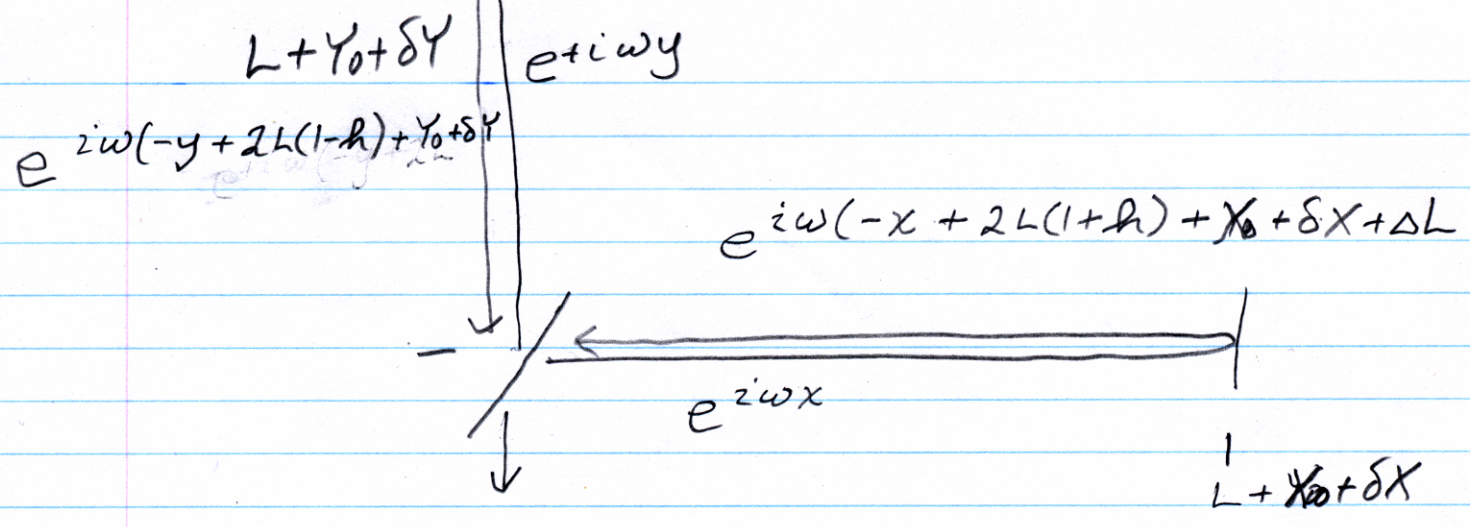
$$A: \frac{a}{\sqrt{4\pi\omega_0}} e^{-i\omega_0(t-x)} + \int \frac{A\hat{\omega} e^{-i(\omega_0+\hat{\omega})(t-x)}}{\sqrt{4\pi(\omega_0+\hat{\omega})}} + H.C.$$

$$B = \int \frac{B\hat{\omega} e^{-i\omega(t-y)}}{\sqrt{4\pi(\omega_0+\hat{\omega})}} + H.C.$$

$$C = \frac{a}{\sqrt{2}} e^{-i\omega_0(t-x)} + \frac{A\hat{\omega} e^{-i(\omega_0+\hat{\omega})(t-x)}}{\sqrt{2}\sqrt{4\pi(\omega_0+\hat{\omega})}} + \int \frac{B\hat{\omega} e^{-i(\omega_0+\hat{\omega})(t-x)}}{\sqrt{2}\sqrt{4\pi(\omega_0+\hat{\omega})}} + H.C.$$

We will assume $|\hat{\omega}| \ll \omega_0$ (10^{-12})

$$D \approx \frac{a}{\sqrt{2}\sqrt{4\pi\omega_0}} e^{-i\omega_0(t-y)} + \int \frac{A\hat{\omega} e^{-i(\omega_0+\hat{\omega})(t-y)}}{\sqrt{4\pi(\omega_0+\hat{\omega})}} - \int \frac{B\hat{\omega} e^{-i(\omega_0+\hat{\omega})(t-y)}}{\sqrt{4\pi(\omega_0+\hat{\omega})}} + H.C.$$



$\delta Y, h, \Delta L$ all small
 $\frac{1}{\omega_0} \gg \Delta L \gg \delta Y, hL$

Return $C e^{i\mu} D e^{i\nu}$

$$\begin{aligned} \begin{pmatrix} A_R \\ B_R \end{pmatrix} &= \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} C e^{i\mu} \\ D e^{i\nu} \end{pmatrix} = \\ &= \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} e^{i\mu} & 0 \\ 0 & e^{i\nu} \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} A \\ B \end{pmatrix} \\ &= \frac{1}{2} \begin{pmatrix} e^{i\mu} + e^{i\nu} & e^{i\mu} - e^{i\nu} \\ e^{i\mu} - e^{i\nu} & e^{i\mu} + e^{i\nu} \end{pmatrix} \begin{pmatrix} A \\ B \end{pmatrix} \end{aligned}$$

Assume $\mu, \nu \ll \pi$

$$B_R \approx \frac{1}{2} (i(\mu - \nu) A + B)$$

$$\begin{aligned} \mu &= \omega_0 (L + X_0) + 2\omega_0 \Delta L + 2\omega_0 \delta X - 2\pi N + \omega_0 L h \\ \nu &= \omega_0 (2L + Y_0) + 2\omega_0 \delta Y - 2\pi N - \omega_0 L h \end{aligned}$$

\uparrow
 signal

$$\mu - \nu = 2\omega_0 \Delta L + 2\omega_0(\delta X - \delta Y) + 4\omega_0 h$$

$$B_R \approx \underbrace{\left(2\omega_0 \Delta L\right)}_{10^{-6}} \frac{a}{\sqrt{4\pi\omega_0}} e^{-i\omega_0(t-y)} + \underbrace{4\omega_0 h}_{\text{signal}} + \text{H.C.}$$

$$+ 2\omega_0(\delta X - \delta Y) \approx 10^{-22} \times 10^{10}$$

$$+ \int \frac{B_{\tilde{\omega}}}{\sqrt{4\pi\omega_0}} e^{-i(\omega_0 + \tilde{\omega})(t+y)} + \text{H.C.}$$

Neglect \times $(2\omega_0 \Delta L) \int A_{\tilde{\omega}} e^{-i(\omega_0 + \tilde{\omega})(t+y)} + \text{H.C.}$

Effect of $B_{\tilde{\omega}}$ and of $(\delta Y - \delta X)$ about same. (depends on freq.)

Pressure on mirror δY .

Pressure = energy density ($c=1$)

$$\frac{1}{2} \left[\left(\frac{\partial \phi}{\partial t}\right)^2 + \left(\frac{\partial \phi}{\partial x}\right)^2 \right]$$

= 0 by boundary cond. at x

$$\phi = \frac{a}{\sqrt{2}\sqrt{4\pi\omega_0}} e^{-i\omega_0(t+L)} + \int \left(\frac{A_{\tilde{\omega}}}{\sqrt{2}} + \frac{B_{\tilde{\omega}}}{\sqrt{2}} \right) e^{-i\tilde{\omega}(t-L)} d\omega.$$

+ H.C.

Frequencies only near 0 will effect the motion of mirror.

When I square ϕ get terms of $e^{2i\omega_0 t}$ and $e^{-2i\omega_0 t}$. They are have negl. effect on mirrors.

(10^{15} Hz pushes have no effect on mirror.

$$\text{Thus } \frac{a\omega_0^2}{8\pi\omega_0} \int (A_{\tilde{\omega}}^+ + B_{\tilde{\omega}}^+) e^{+i\tilde{\omega}(t-L)} + \frac{a^*\omega_0^2}{8\pi\omega_0} \int (A_{\tilde{\omega}} + B_{\tilde{\omega}}) e^{-i\tilde{\omega}(t-L)}$$

At freq $\tilde{\omega}$, the force is

$$\frac{a\omega_0}{8\pi\omega_0} (A_{\tilde{\omega}} + B_{\tilde{\omega}}) + \frac{a^*\omega_0}{8\pi\omega_0} (A_{-\tilde{\omega}}^+ + B_{-\tilde{\omega}}^+)$$

Assume a real

If $\tilde{\omega} \gg \Omega$

$$M\delta\ddot{x} = F$$

$$\text{or } \delta x_{\tilde{\omega}} = \frac{a\omega_0}{M8\pi\tilde{\omega}^2} [A_{\tilde{\omega}}^+ A_{-\tilde{\omega}} + B_{\tilde{\omega}} + B_{-\tilde{\omega}}^+]$$

(the

Similarly for δY .

$$\delta Y_{\hat{\omega}} = \frac{a \omega_0}{M 8\pi \hat{\omega}^2} \left[A_{\hat{\omega}} + A_{-\hat{\omega}}^\dagger + B_{\hat{\omega}} - B_{-\hat{\omega}}^\dagger \right]$$

I.e.

$$\delta X_{\hat{\omega}} - \delta Y_{\hat{\omega}} = \frac{2 a \omega_0}{M 8\pi \hat{\omega}^2} (B_{\hat{\omega}} + B_{-\hat{\omega}}^\dagger)$$

I.e. Radu pressure noise is

$$\text{prop to } (B_{\hat{\omega}} + B_{-\hat{\omega}}^\dagger) \frac{a \omega_0}{8\pi M \hat{\omega}^2}$$

Similarly the "shot noise" is also equal to $B_{\hat{\omega}} + B_{-\hat{\omega}}^\dagger$

$$\langle B_{\hat{\omega}} + B_{-\hat{\omega}}^\dagger \rangle = 0$$

$$\langle (B_{\hat{\omega}} + B_{-\hat{\omega}}^\dagger)^\dagger (B_{\hat{\omega}} + B_{-\hat{\omega}}^\dagger) \rangle \neq 0$$

If state is vacuum state

$$\langle 0 | (B_{\hat{\omega}}^\dagger + B_{-\hat{\omega}}) (B_{\hat{\omega}} + B_{-\hat{\omega}}^\dagger) | 0 \rangle$$

$$= \langle 0 | B_{-\hat{\omega}} \cdot B_{-\hat{\omega}}^\dagger | 0 \rangle = 1$$

Create Squeezed state.

$$|S\rangle = \frac{1}{N} e^{r B_{\omega}^{\dagger} B_{-\omega}^{\dagger}} |0\rangle$$

$$\left(\langle 0 | e^{r^* B_{\omega} B_{-\omega}} e^{r B_{\omega}^{\dagger} B_{-\omega}^{\dagger}} | 0 \rangle \right)$$

$$= \langle 0 | \sum_{nm} r^{*n} \frac{(B_{\omega} B_{-\omega})^n}{n!} r^m \frac{B_{\omega}^{\dagger} B_{-\omega}^{\dagger}{}^m}{m!} | 0 \rangle$$

$$= \langle 0 | \sum_n |r|^{2n} \frac{B_{\omega}^n B_{-\omega}^{\dagger n} B_{-\omega}^n B_{\omega}^{\dagger n}}{(n!)^2} | 0 \rangle$$

$$= \langle 0 | \sum_{n=0}^{\infty} |r|^{2n} | 0 \rangle = \frac{1}{1-|r|^2} \quad (|r| < 1)$$

$$N = \sqrt{1-|r|^2}$$

$$\langle S | (B_{\omega} + B_{-\omega}^{\dagger})(B_{\omega}^{\dagger} + B_{-\omega}) | S \rangle$$

$$r = \tanh \theta \quad B (\cosh \theta B_{\omega} - \sinh \theta B_{-\omega}^{\dagger}) | S \rangle = 0$$

$$(\cos \theta B_{-\omega} + \sinh \theta B_{\omega}^{\dagger}) | S \rangle = 0$$

$$\tilde{B}_1 = \cosh \theta B_{\omega} - \sinh \theta B_{-\omega}^{\dagger}$$

$$\tilde{B}_2 = \cos \theta B_{-\omega} + \sinh \theta B_{\omega}^{\dagger}$$

$$[B_1, B_1^{\dagger}] = 1, \quad [B_2, B_2^{\dagger}] = 1$$

$$[B_1, B_2] = [B_1, B_2^{\dagger}] = 0$$

$$B_1 |S\rangle = B_2 S.$$

$$B\hat{\omega} + B_{-\hat{\omega}}^{\dagger} = (B_1 + B_2^{\dagger}) e^{-\theta}$$

$$(B\omega + B_{-\omega}^{\dagger})(B_{\omega}^{\dagger} + B_{-\omega}) = e^{-2\theta} (B_1^{\dagger} + B_2)(B_1 + B_2^{\dagger})$$

$$\langle S | (B_{\omega}^{\dagger} + B_{-\omega})(B\omega + B_{-\omega}^{\dagger}) | S \rangle$$

$$= e^{-2\theta} \quad \text{If } r = \tanh\theta$$

then squeezed state can reduce the noise by almost arbitrary amount. This reduces both the ~~radar~~ shot noise and the pressure noise.

It depends on the beam splitter transfer function being real $\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$

Can also have $\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -i \\ 1 & -i \end{pmatrix}$

Then Radu pressure noise is

turns out to be $\frac{\alpha_i}{M\omega^2} (B_{\omega} - B_{-\omega}^{\dagger})$

while shot noise is still $\frac{a}{16z} (B_{\omega} + B_{-\omega}^+)$

$$\langle S | (B_{\omega} - B_{-\omega}^+)^{\dagger} (B_{\omega} - B_{-\omega}) | S \rangle$$

$$= e^{+r} \quad \text{I.e. bigger.}$$

thus if beam splitter is imag parts
 Need squeezing to vary with freq
 Need freq dep squeezing to
 squeezing which kills shot noise
 at high freq + Radn pressure at
 low freq.